

1 Incremental Algorithm

Definition 1 Let $X = [(\mathbf{a}_1, b_1), \dots, (\mathbf{a}_N, b_N)]$, where $\mathbf{a}_i \in \mathbb{R}^n, b_i \in \mathbb{R}$ for $i = 1, \dots, N$. Let $V = \{i_1, \dots, i_s\} \subseteq \{1, \dots, n\}$ for some $1 \leq i_1 < i_2 < \dots < i_s \leq n$, and define the projection

$$\pi_V : \mathbb{R}^n \longrightarrow \mathbb{R}^s, \quad \pi_V(x_1, \dots, x_n) = (x_{i_1}, \dots, x_{i_s}).$$

We say that the set V is *separating* for X if for all $1 \leq i, j \leq N$

$$b_i \neq b_j \quad \Rightarrow \quad \pi_V(\mathbf{a}_i) \neq \pi_V(\mathbf{a}_j).$$

We say that V is a *minimal separating set* for X if V is separating but no proper subset of V is separating for X .

Algorithm 2 MinSepSet (incremental)

INPUT: $X = [(\mathbf{a}_1, b_1), \dots, (\mathbf{a}_N, b_N)]$, where $\mathbf{a}_i \in \mathbb{R}^n, b_i \in \mathbb{R}$ for $i = 1, \dots, N$.

OUTPUT: $\mathcal{S} = [V_1, \dots, V_t]$ such that the entries of \mathcal{S} form the set of all minimal separating sets for X . Also, $|V_i| \leq |V_j|$ if $i < j$.

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if  $N = 1$  then
  return  $[\emptyset]$ 
end if
 $\mathcal{S} := []$ 
 $\mathcal{T} := \text{MinSepSet}([(a_1, b_1), \dots, (a_{N-1}, b_{N-1})])$ 
for  $i=1$  to  $|\mathcal{T}|$  do
   $V := \mathcal{T}[i]$ 
   $G_V := \emptyset$ 
  for  $j=1$  to  $N-1$  do
    if  $b_j \neq b_N$  and  $\pi_V(\mathbf{a}_j) = \pi_V(\mathbf{a}_N)$  then
       $G_V := G_V \cup \{j\}$ 
    end if
  end for
  if  $G_V = \emptyset$  then
     $\mathcal{S} := \text{Insert\&Reduce}(\mathcal{S}, V)$ 
  end if
  if  $G_V = \{j_1\}$  then
    for  $k=1$  to  $n$  do
      if  $\pi_{\{k\}}(\mathbf{a}_{j_1}) \neq \pi_{\{k\}}(\mathbf{a}_N)$  then
         $\mathcal{S} := \text{Insert\&Reduce}(\mathcal{S}, V \cup \{k\})$ 
      end if
    end for
  end if
  if  $G_V = \{j_1, \dots, j_s\}$  and  $s \geq 2$  then
     $\bar{V} := \{1, \dots, n\} - V$ 

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 $\mathcal{P} := \text{MinSepSet}([( \pi_{\bar{V}}(\mathbf{a}_N), b_N), (\pi_{\bar{V}}(\mathbf{a}_{j_1}), b_{j_1}), \dots, (\pi_{\bar{V}}(\mathbf{a}_{j_s}), b_{j_s})])$ 
for  $j=1$  to  $|\mathcal{P}|$  do
   $\mathcal{S} := \text{Insert\&Reduce}(\mathcal{S}, V \cup \mathcal{P}[j])$ 
end for
end if
end for
return  $\mathcal{S}$ 

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Definition 3 Let $\mathcal{S} = [S_1, \dots, S_t]$ be a list of finite sets. We say that \mathcal{S} is *reduced* if for all $i < j$ we have $|S_i| \leq |S_j|$ and $S_i \not\subseteq S_j$.

For \mathcal{S} as above, V a finite set and $i \in \{1, \dots, t, t+1\}$, the subroutine $\text{Insert}(\mathcal{S}, V, i)$ inserts V to the i -th place of \mathcal{S} , moving the S_i, \dots, S_t one to the right. For $i = t+1$ it inserts V to the end of the list \mathcal{S} .

The subroutine $\text{Remove}(\mathcal{S}, S_i)$ finds and removes S_i from \mathcal{S} , keeping the order of the rest of the list.

Algorithm 4 Insert&Reduce

INPUT: $\mathcal{S} = [S_1, \dots, S_t]$ a reduced list of finite sets, and V a finite set.

OUTPUT: If $\exists S_i$ such that $S_i \subseteq V$ then return \mathcal{S} , otherwise the elements of $\{V\} \cup \{S_i : V \not\subseteq S_i\}$ ordered by their cardinality.

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if  $|S| = 0$  then
  return  $[V]$ 
end if
 $\text{flag} := 0$ 
 $j := 1$ 
for  $i=1$  to  $|S|$  do
  if  $S_i \subseteq V$  then
    return  $\mathcal{S}$ 
  end if
  if  $\text{flag} = 0$  and  $|S_i| \geq |V|$  then
     $\mathcal{S}'_j := V$ 
     $\text{flag} := 1$ 
  end if
  if  $\text{flag} = 1$  and  $V \not\subseteq S_i$  then
     $\mathcal{S}'_j := S_i$ 
  end if
   $j := j + 1$ 
end for
if  $\text{flag} = 0$  then
   $\mathcal{S}'_{j+1} := V$ 
end if
return  $\mathcal{S}'$ 

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